



WEBINAR PRESENTATION

JUNE 11, 2020, 02:00 PM – 04:00 PM

Organized By

Department of Electrical and Electronics Engineering
RGM COLLEGE OF ENGINEERING AND TECHNOLOGY, NANDYAL

In Association With

SIMULATION OF POWER CONVERTERS USING PYTHON

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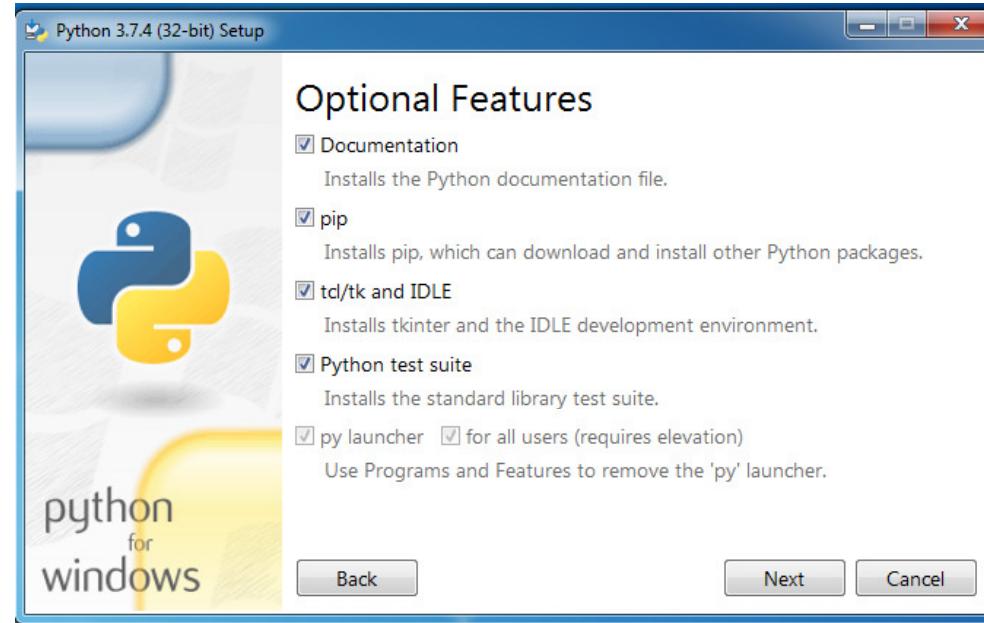
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INSTALL PYTHON



<https://www.anaconda.com/products/individual#windows>



INSTALL numpy Package

Final GUI wp.py - D:\Python Program\Final_GUI_wp.py (3.7.4)
Python 3.7.4 Shell

```
File Edit Shell Debug Options Window Help
Python 3.7.4 (tags/v3.7.4:e09359112e, Jul  8 2019, 19:29:22) [MSC v.1916 32 bit
(Intel)] on win32
Type "help", "copyright", "credits" or "license()" for more information.
>>>
=====
RESTART: D:\Python Program\Final_GUI_wp.py =====
Traceback (most recent call last):
  File "D:\Python Program\Final_GUI_wp.py", line 2, in <module>
    import numpy as np
ModuleNotFoundError: No module named 'numpy'
>>>
```

cmd Command Prompt - pip3 install numpy

```
Microsoft Windows [Version 6.1.7601]
Copyright (c) 2009 Microsoft Corporation. All rights reserved.

C:\Users\Admin>pip3 install numpy
Collecting numpy
  Downloading https://files.pythonhosted.org/packages/23/2e/41a977865a8ad0ac98b3
f9ae421415cd2cd3f195b179a6b5f3aafb7922d7(numpy-1.18.5-cp37-cp37m-win32.whl (10.8
MB)
  28x ! [██████████] 3.1MB 63kB/s eta 0:02:01
```

PIP3 install numpy



MATLAB	NumPy	Notes
<code>ndims(a)</code>	<code>ndim(a)</code> or <code>a.ndim</code>	get the number of dimensions of an array
<code>numel(a)</code>	<code>size(a)</code> or <code>a.size</code>	get the number of elements of an array
<code>size(a)</code>	<code>shape(a)</code> or <code>a.shape</code>	get the "size" of the matrix
<code>size(a,n)</code>	<code>a.shape[n-1]</code>	get the number of elements of the n-th dimension of array <code>a</code> . (Note that MATLAB® uses 1 based indexing while Python uses 0 based indexing, See note INDEXING)
<code>[1 2 3; 4 5 6]</code>	<code>array([[1.,2.,3.], [4.,5.,6.]])</code>	2x3 matrix literal
<code>[a b; c d]</code>	<code>block([[a,b], [c,d]])</code>	construct a matrix from blocks <code>a</code> , <code>b</code> , <code>c</code> , and <code>d</code>
<code>a(end)</code>	<code>a[-1]</code>	access last element in the 1xn matrix <code>a</code>
<code>a(2,5)</code>	<code>a[1,4]</code>	access element in second row, fifth column
<code>a(2,:)</code>	<code>a[1]</code> or <code>a[1,:]</code>	entire second row of <code>a</code>
<code>a(1:5,:)</code>	<code>a[0:5]</code> or <code>a[:5]</code> or <code>a[0:5,:]</code>	the first five rows of <code>a</code>
<code>a(end-4:end,:)</code>	<code>a[-5:]</code>	the last five rows of <code>a</code>
<code>a(1:3,5:9)</code>	<code>a[0:3][:,4:9]</code>	rows one to three and columns five to nine of <code>a</code> . This gives read-only access.
<code>a([2,4,5],[1,3])</code>	<code>a[ix_([1,3,4],[0,2])]</code>	rows 2,4 and 5 and columns 1 and 3. This allows the matrix to be modified, and doesn't require a regular slice.



<code>a(3:2:21,:)</code>	<code>a[2:21:2,:]</code>	every other row of <code>a</code> , starting with the third and going to the twenty-first
<code>a(1:2:end,:)</code>	<code>a[::2,:]</code>	every other row of <code>a</code> , starting with the first
<code>a(end:-1:1,:)</code> or <code>flipud(a)</code>	<code>a[::-1,:]</code>	<code>a</code> with rows in reverse order
<code>a([1:end-1],:)</code>	<code>a[r_[len(a),0]]</code>	<code>a</code> with copy of the first row appended to the end
<code>a.'</code>	<code>a.transpose() or a.T</code>	transpose of <code>a</code>
<code>a'</code>	<code>a.conj().transpose() or a.conj().T</code>	conjugate transpose of <code>a</code>
<code>a * b</code>	<code>a @ b</code>	matrix multiply
<code>a .* b</code>	<code>a * b</code>	element-wise multiply
<code>a./b</code>	<code>a/b</code>	element-wise divide
<code>a.^3</code>	<code>a**3</code>	element-wise exponentiation
<code>(a>0.5)</code>	<code>(a>0.5)</code>	matrix whose i,j th element is $(a_{ij} > 0.5)$. The Matlab result is an array of 0s and 1s. The NumPy result is an array of the boolean values <code>False</code> and <code>True</code> .
<code>find(a>0.5)</code>	<code>nonzero(a>0.5)</code>	find the indices where $(a > 0.5)$
<code>a(:,find(v>0.5))</code>	<code>a[:,nonzero(v>0.5)[0]]</code>	extract the columns of <code>a</code> where vector <code>v > 0.5</code>
<code>a(:,find(v>0.5))</code>	<code>a[:,v.T>0.5]</code>	extract the columns of <code>a</code> where column vector <code>v > 0.5</code>
<code>a(a<0.5)=0</code>	<code>a[a<0.5]=0</code>	<code>a</code> with elements less than 0.5 zeroed out



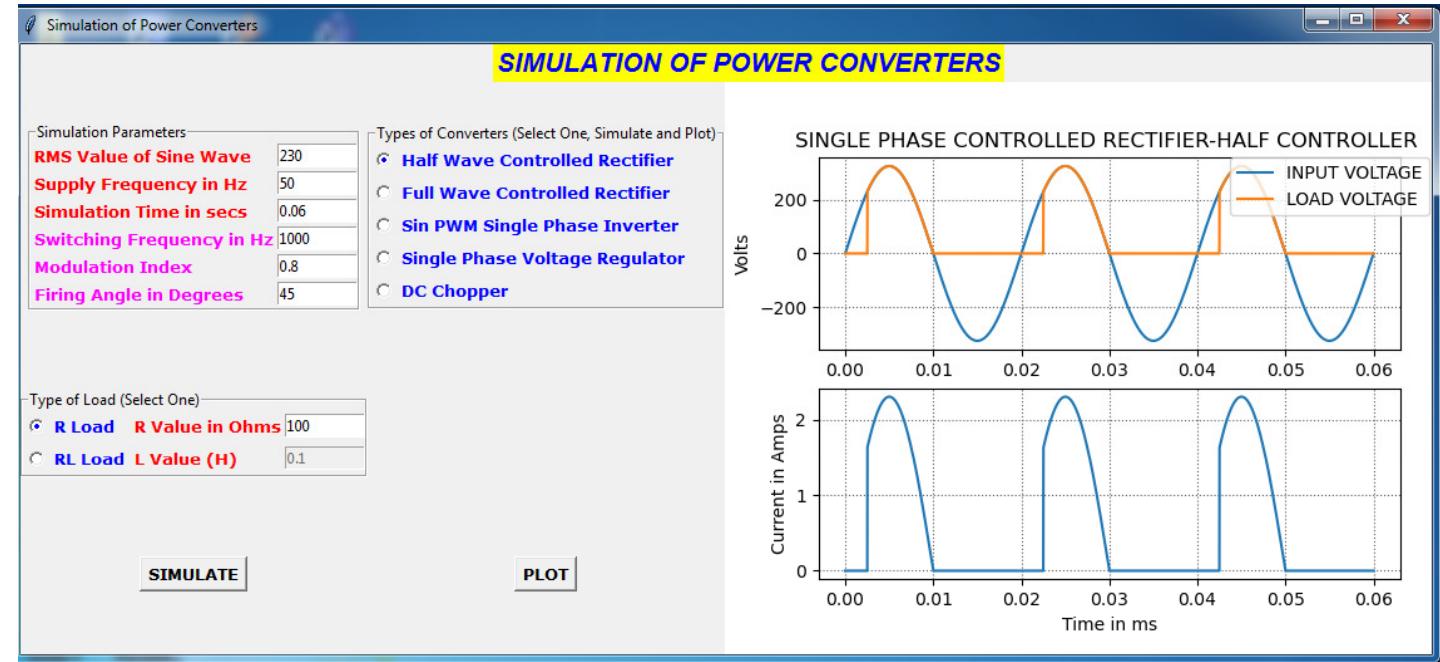
<code>a .* (a>0.5)</code>	<code>a * (a>0.5)</code>	a with elements less than 0.5 zeroed out
<code>a[:] = 3</code>	<code>a[:] = 3</code>	set all values to the same scalar value
<code>y=x</code>	<code>y = x.copy()</code>	numpy assigns by reference
<code>y=x(2,:)</code>	<code>y = x[1,:].copy()</code>	numpy slices are by reference
<code>y=x(:)</code>	<code>y = x.flatten()</code>	turn array into vector (note that this forces a copy)
<code>1:10</code>	<code>arange(1.,11.) or r_[1.:11.] or r_[1:10:10j]</code>	create an increasing vector (see note RANGES)
<code>0:9</code>	<code>arange(10.) or r_[:10.] or r_[:9:10j]</code>	create an increasing vector (see note RANGES)
<code>[1:10]'</code>	<code>arange(1.,11.):, newaxis]</code>	create a column vector
<code>zeros(3,4)</code>	<code>zeros((3,4))</code>	3x4 two-dimensional array full of 64-bit floating point zeros
<code>zeros(3,4,5)</code>	<code>zeros((3,4,5))</code>	3x4x5 three-dimensional array full of 64-bit floating point zeros
<code>ones(3,4)</code>	<code>ones((3,4))</code>	3x4 two-dimensional array full of 64-bit floating point ones
<code>eye(3)</code>	<code>eye(3)</code>	3x3 identity matrix
<code>diag(a)</code>	<code>diag(a)</code>	vector of diagonal elements of a
<code>diag(a,0)</code>	<code>diag(a,0)</code>	square diagonal matrix whose nonzero values are the elements of a
<code>rand(3,4)</code>	<code>random.rand(3,4) or random.random_sample((3, 4))</code>	random 3x4 matrix



Importing Packages

```
import numpy as np
import tkinter as tk
import math
```

```
from pylab import *
from scipy.optimize import *
from matplotlib import *
```

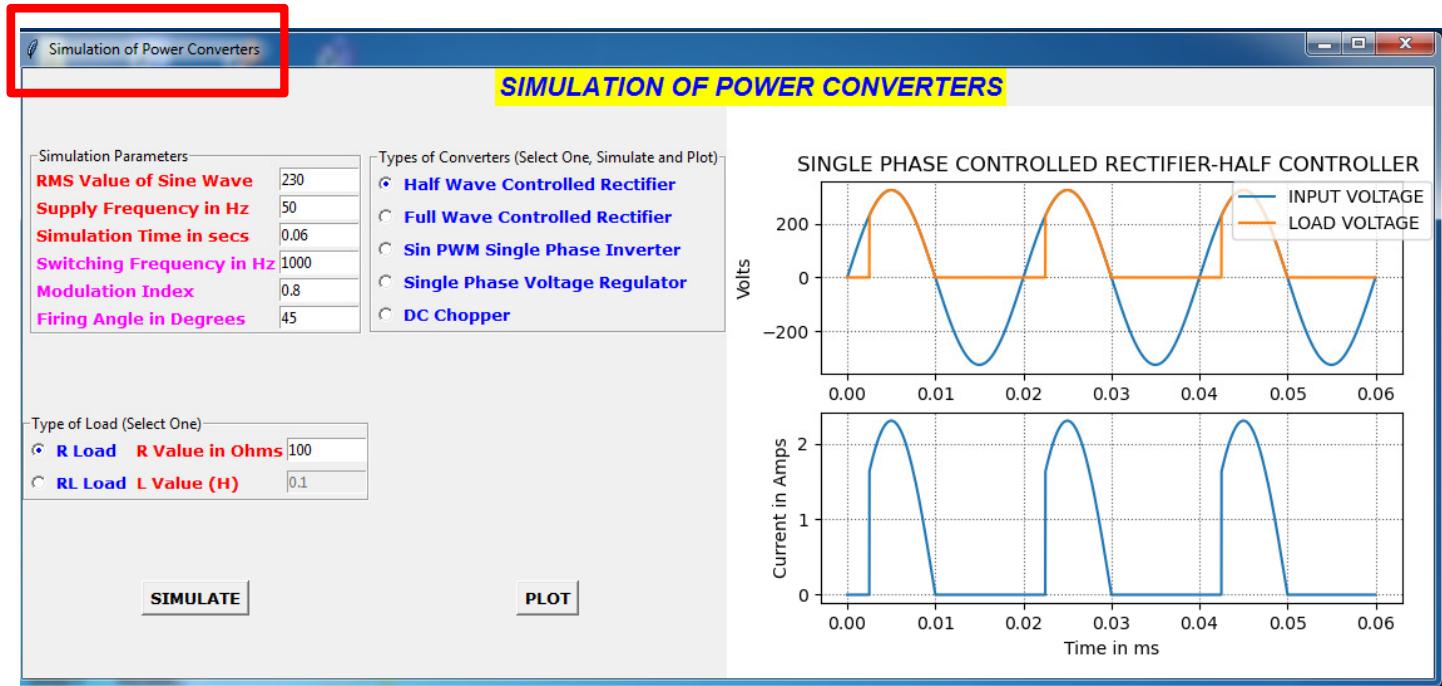




Initializing Window

```
import numpy as np
import tkinter as tk
import math
```

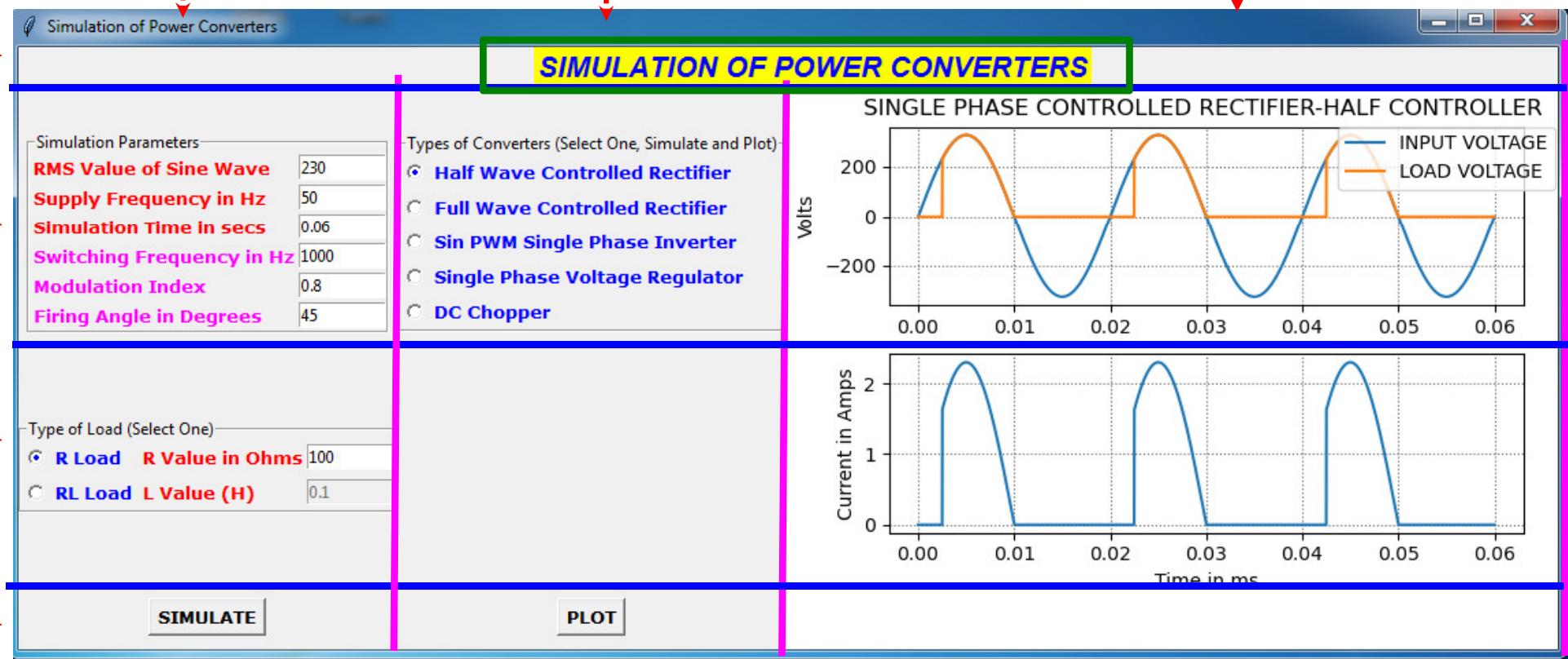
```
from pylab import *
from scipy.optimize import *
from matplotlib import *
```



```
win =tk.Tk()
win.title("Simulation of Power Converters")
```



```
a_title=tk.Label(win,text='SIMULATION OF POWER CONVERTERS', fg = "blue",bg = "yellow",font = "Helvetica 16 bold italic")  
a_title.grid(column=0, row=0, columnspan=3)
```

Column 0**Column 1****Column 2****Row 0**



```
mighty = tk.LabelFrame(win, text='Simulation Parameters')
```

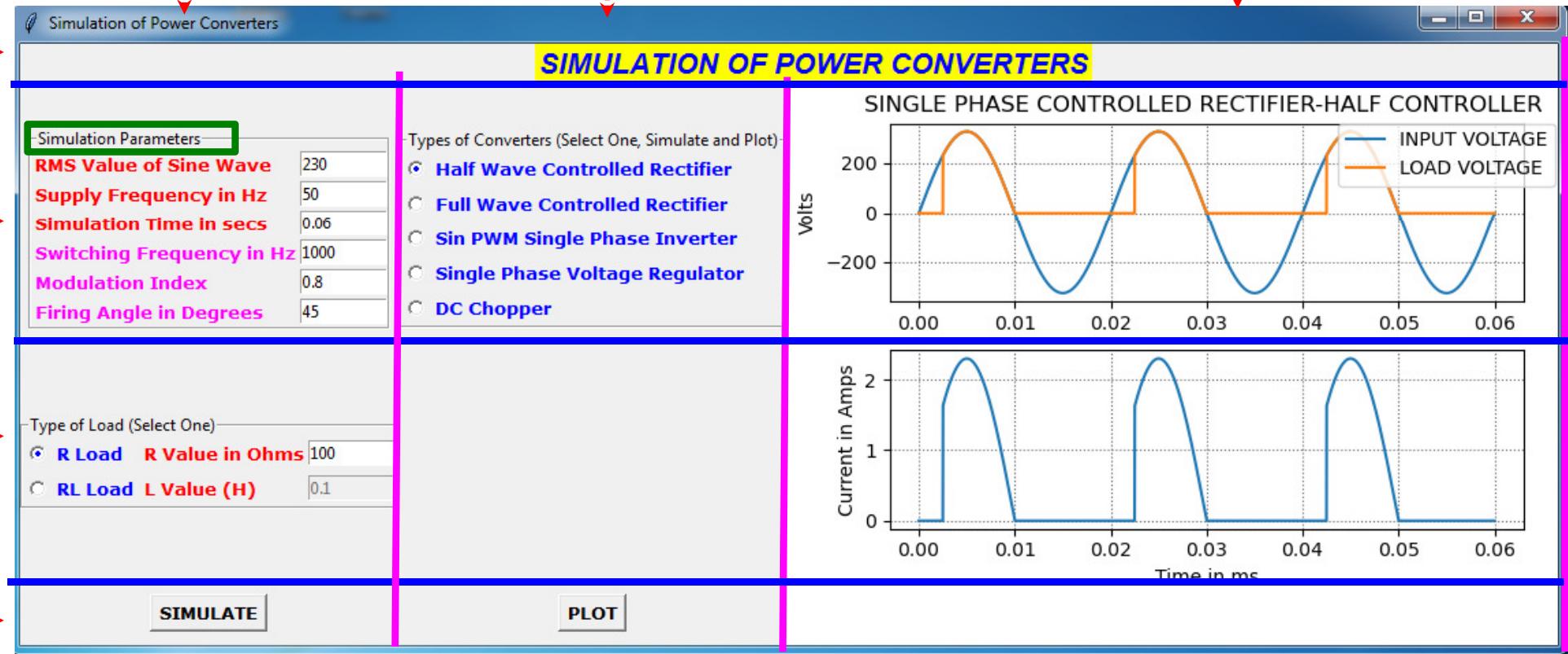
```
mighty.grid(column=0, row=1)
```

Column 0

Column 1

Column 2

Row 0



Row 2

Row 3



contypes = tk.LabelFrame(win, text="Types of Converters (Select One, Simulate and Plot)")

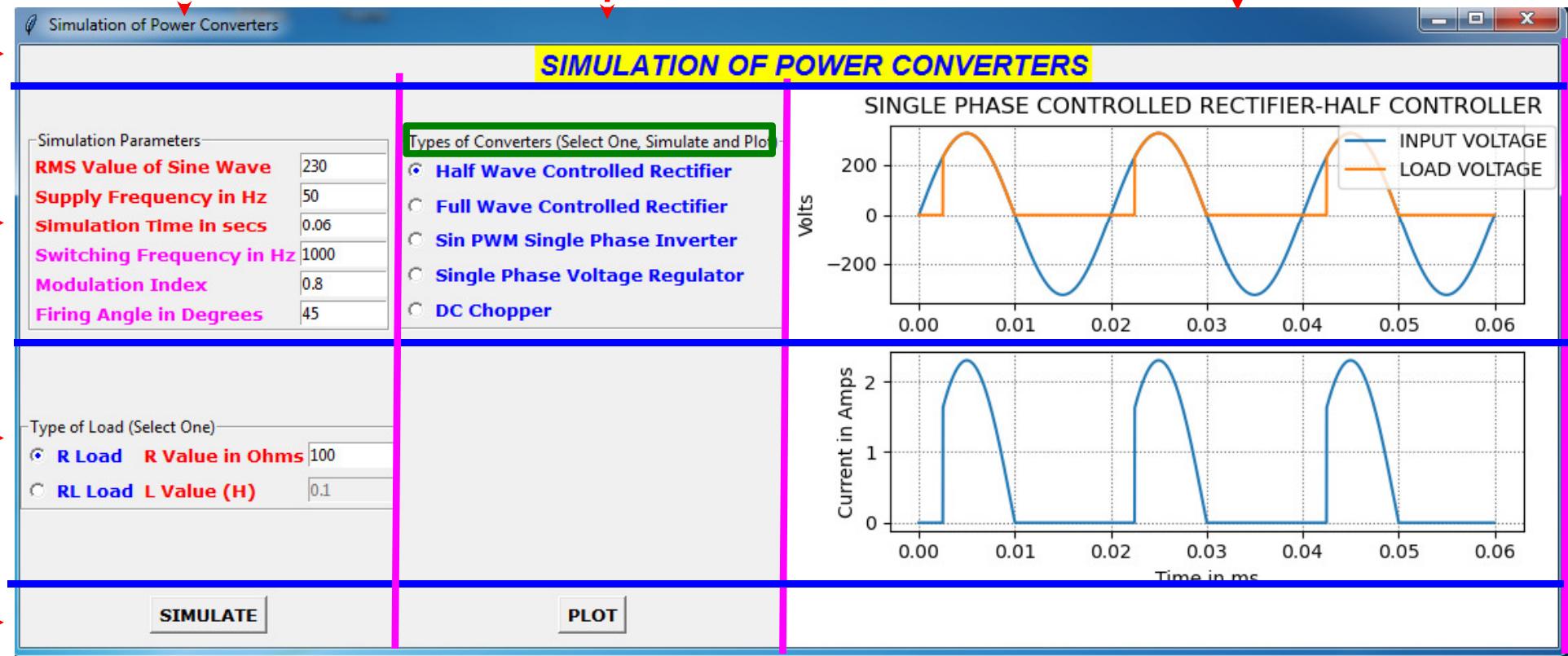
contypes.grid(column=1, row=1)

Column 0

Column 1

Column 2

Row 0





```
res = tk.LabelFrame(win, text='Plot Area')
```

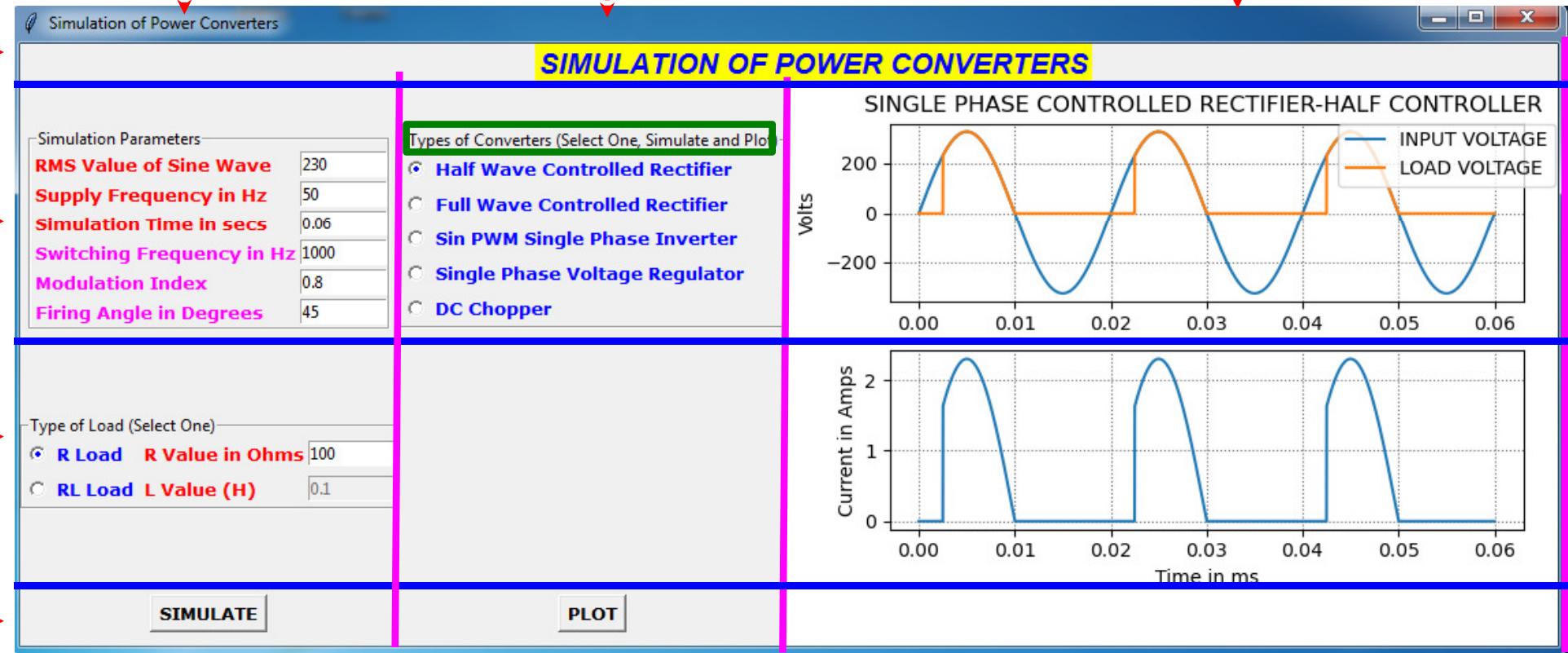
```
res.grid(column=2, row=1, rowspan=3)
```

Column 0

Column 1

Column 2

Row 0



Row 1

Row 2

Row 3



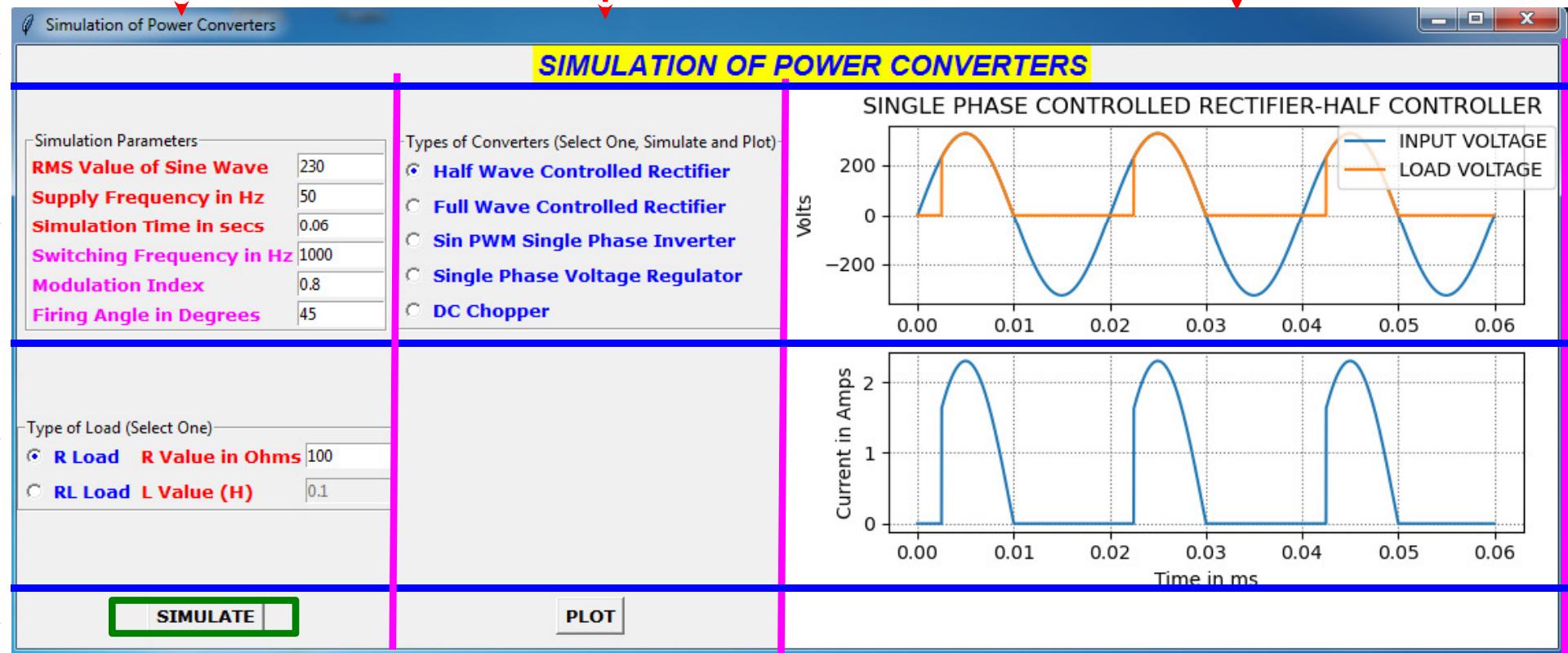
```
btn = tk.Button(win, text='SIMULATE', command=simulate, font = "Verdana 10 bold")
btn.grid(column=0, row=3)
```

Column 0

Column 1

Column 2

Row 0



Row 1

Row 2

Row 3



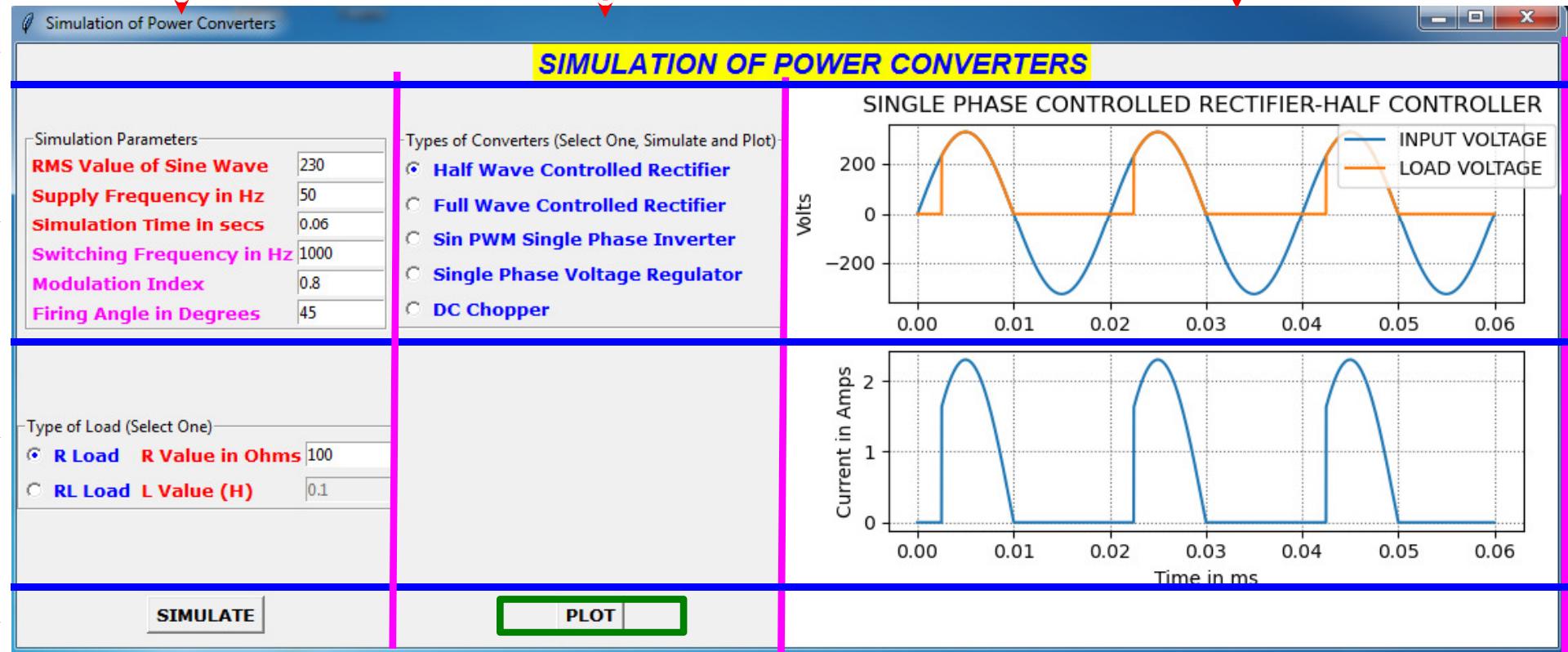
```
btn1 = tk.Button(win, text="PLOT", command=plt1, font = "Verdana 10 bold")
btn1.grid(column=1, row=3)
```

Column 0

Column 1

Column 2

Row 0



Row 1

Row 2

Row 3



```
a_input = tk.Label(mighty, text="RMS Value of Sine Wave",font = "Verdana 10 bold",fg = "red")
a_input.grid(column=0, row=0, sticky=tk.W)
```

```
peamp = tk.Entry(mighty,width=10)
peamp.insert(0,"230")
peamp.grid(column=1, row=0)
```

```
a_supply = tk.Label(mighty, text="Supply Frequency in Hz",font = "Verdana 10 bold",fg = "red",justify=tk.LEFT)
a_supply.grid(column=0, row=1, sticky=tk.W)
```

```
freq = tk.Entry(mighty,width=10)
freq.insert(0,"50")
freq.grid(column=1, row=1)
```

Simulation Parameters

R0	RMS Value of Sine Wave	230
R1	Supply Frequency in Hz	50
R2	Simulation Time in secs	0.06
R3	Switching Frequency in Hz	1000
R4	Modulation Index	0.8
R5	Firing Angle in Degrees	45



```
a_time = tk.Label(mighty, text="Simulation Time in secs",font = "Verdana 10 bold",fg = "red")
a_time.grid(column=0, row=2, sticky=tk.W)
```

```
simtime = tk.Entry(mighty,width=10)
simtime.insert(0,"0.06")
simtime.grid(column=1, row=2)
```

```
a_freq = tk.Label(mighty, text="Switching Frequency in Hz",font = "Verdana 10 bold",fg = "magenta")
a_freq .grid(column=0, row=3, sticky=tk.W)
```

```
sf = tk.Entry(mighty,width=10)
sf.insert(0,"1000")
sf.grid(column=1, row=3)
```

Simulation Parameters

R0	RMS Value of Sine Wave	230
R1	Supply Frequency in Hz	50
R2	Simulation Time in secs	0.06
R3	Switching Frequency in Hz	1000
R4	Modulation Index	0.8
R5	Firing Angle in Degrees	45



```
a_mi = tk.Label(mighty, text="Modulation Index",font = "Verdana 10 bold",fg = "magenta",justify=tk.LEFT)
a_mi.grid(column=0, row=4, sticky=tk.W)
```

```
m = tk.Entry(mighty,width=10)
m.insert(0,"0.8")
m.grid(column=1, row=4)
```

Simulation Parameters	
R0	RMS Value of Sine Wave
R1	Supply Frequency in Hz
R2	Simulation Time in secs
R3	Switching Frequency in Hz
R4	Modulation Index
R5	Firing Angle in Degrees

C0 C1

```
a_fire = tk.Label(mighty, text="Firing Angle in Degrees",font = "Verdana 10 bold",fg = "magenta")
a_fire.grid(column=0, row=5, sticky=tk.W)
```

```
alpha = tk.Entry(mighty,width=10)
alpha.insert(0,"45")
alpha.grid(column=1, row=5)
```



```

selected = tk.IntVar()
rad1 = tk.Radiobutton(contypes,text='Half Wave Controlled Rectifier', value=1, variable=selected,
                      font = "Verdana 10 bold",fg = "blue",)
rad2 = tk.Radiobutton(contypes,text='Full Wave Controlled Rectifier', value=2, variable=selected,
                      font = "Verdana 10 bold",fg = "blue")
rad3 = tk.Radiobutton(contypes,text='Sin PWM Single Phase Inverter', value=3, variable=selected,
                      font = "Verdana 10 bold",fg = "blue")
rad4 = tk.Radiobutton(contypes,text='Single Phase Voltage Regulator', value=4, variable=selected,
                      font = "Verdana 10 bold",fg = "blue")
rad5 = tk.Radiobutton(contypes,text='DC Chopper', value=5, variable=selected, font = "Verdana 10 bold",
                      fg = "blue")
rad1.grid(column=0, row=1, sticky=tk.W)
rad2.grid(column=0, row=2, sticky=tk.W)
rad3.grid(column=0, row=3, sticky=tk.W)
rad4.grid(column=0, row=4, sticky=tk.W)
rad5.grid(column=0, row=5, sticky=tk.W)
selected.set(1)

```

Types of Converters (Select One, Simulate and Plot)

- Half Wave Controlled Rectifier**
- Full Wave Controlled Rectifier**
- Sin PWM Single Phase Inverter**
- Single Phase Voltage Regulator**
- DC Chopper**



```

loadchoice = tk.IntVar()
load1 = tk.Radiobutton(loadtype,text='R Load', value=1, variable=loadchoice,font = "Verdana 10 bold",fg = "blue",
command=sel)
load2 = tk.Radiobutton(loadtype,text='RL Load', value=2, variable=loadchoice,font = "Verdana 10 bold",fg = "blue",
command=sel)
load1.grid(column=0, row=1, sticky=tk.W)
load2.grid(column=0, row=2, sticky=tk.W)
loadchoice.set(2)

r_input = tk.Label(loadtype, text="R Value in Ohms",font = "Verdana 10 bold",fg = "red")
r_input.grid(column=1, row=1, sticky=tk.W)
rvalue = tk.Entry(loadtype,width=10)
rvalue.insert(0,"100")
rvalue.grid(column=3, row=1)
l_input = tk.Label(loadtype, text="L Value (H)",font = "Verdana 10 bold",fg = "red")

l_input.grid(column=1, row=2, sticky=tk.W)
lvalue = tk.Entry(loadtype,width=10)
lvalue.insert(0,"0.1")
lvalue.grid(column=3, row=2)

```





```
def sel():
    global l
    l = int(loadchoice.get())
    if l==1:
        lvalue.config(state='disabled')
    else:
        lvalue.config(state='normal')
```

Type of Load (Select One)

R Load R Value in Ohms

RL Load L Value (H)

Type of Load (Select One)

R Load R Value in Ohms

RL Load L Value (H)

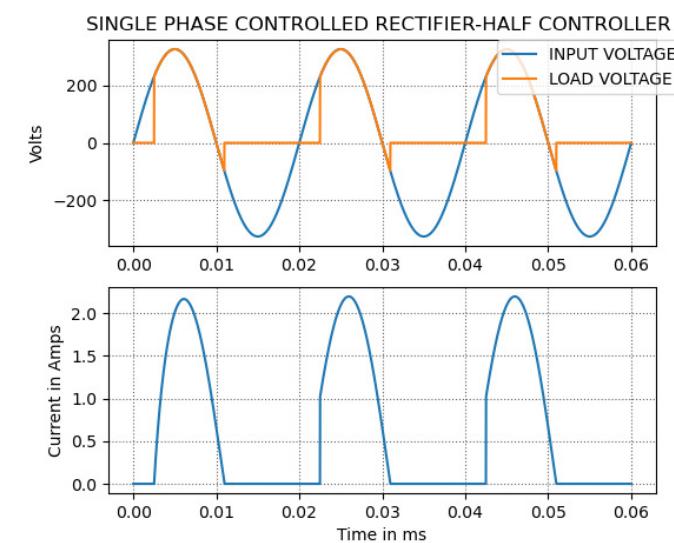


```

fig = Figure(figsize=(6, 5), dpi=100)
a1 = fig.add_subplot(211)
a1.plot(time, amplitude2,label="INPUT VOLTAGE")
a1.plot(time , amplitude3, label="LOAD VOLTAGE")
a1.set_title('SINGLE PHASE CONTROLLED RECTIFIER-HALF CONTROLLER ')
a1.set_ylabel('Volts')
a1.legend(bbox_to_anchor=(1.05, 1), loc='upper right', borderaxespad=0.)
a1.grid(b=True, which='major', color='#666666', linestyle=':')

a3 = fig.add_subplot(212)
a3.plot(time, Icurrent,label="Load Current")
a3.set_xlabel('Time in ms')
a3.set_ylabel('Current in Amps')
a3.grid(b=True, which='major', color='#666666', linestyle=':')

```





```

def func(b):
    k = int(loadchoice.get())
    a1=math.radians(int(alpha.get()))
    fr=int(freq.get())
    L1=float(lvalue.get())
    R1=float(rvalue.get())
    if k==1:
        langle = (math.atan(2*math.pi*fr*0/R1))
    else:
        langle = (math.atan(2*math.pi*fr*L1/R1))

    r1=(a1-b)/math.tan(langle)
    return math.sin(langle-b)-(math.sin(langle-a1)*math.exp(r1))

    beta = (fsolve(func, 3.14))

```

For $\alpha \leq \omega t \leq \beta$

$$Ri_o + L \frac{di_o}{dt} = v_o = \sqrt{2}V_i \sin\omega t \quad (10.11)$$

The general solution of which is given by

$$i_o = I_0 e^{\frac{(\omega t - \alpha)}{\tan \varphi}} + \frac{\sqrt{2}V_i}{Z} \sin(\omega t - \varphi) \quad (10.12)$$

$$\text{Where } \tan \varphi = \frac{\omega L}{R} \text{ and } Z = \sqrt{R^2 + \omega^2 L^2}$$

$$i_o|_{\omega t = \alpha} = 0$$

$$\therefore 0 = I_0 + \frac{\sqrt{2}V_i}{Z} \sin(\alpha - \varphi)$$

$$\therefore i_o = \frac{\sqrt{2}V_i}{Z} \left[\sin(\varphi - \alpha) e^{\frac{(\omega t - \alpha)}{\tan \varphi}} + \sin(\omega t - \varphi) \right] \quad (10.13)$$

$i_o = 0$ otherwise.

Equation (10.13) can be used to find out $I_{o\text{rms}}$. To find out β it is noted that

$$i_o|_{\omega t = \beta} = 0$$

$$\therefore \sin(\varphi - \alpha) e^{\frac{\alpha - \beta}{\tan \varphi}} = \sin(\varphi - \beta) \quad (10.14)$$



```

def simulate():
    global s, l, time, amplitude1, amplitude2, amplitude3, amplitude4, amplitude5, lcurrent
    s= int(selected.get())
    l = int(loadchoice.get())
    tt = float(simtime.get())
    if s==1:
        V= float(peamp.get())
        f1=int(freq.get())
        a=int(alpha.get())
        L=float(lvalue.get())
        R=float(rvalue.get())
        if l==1:
            langle = (math.atan(2*math.pi*f1*L/R))
            L=0
        else:
            langle = (math.atan(2*math.pi*f1*L/R))
            beta = (fsolve(func, 3.14))
            print(beta)
            time = np.arange(0, tt, 0.00001);
            P=2/f1
            amplitude1=(360*(P-abs((time*2%P)-P)))/P

```

$$y = \frac{A \cdot (P - |(x \bmod (2 \cdot P)) - P|)}{P}$$



```

amplitude2= V*math.sqrt(2)*(np.sin(2*math.pi*f1*time))
Z = math.sqrt((R*R)+(2*math.pi*f1*2*math.pi*f1*L*L))
ad = math.radians(a)
x1 = sin((2*math.pi*f1*time)-langle)
x2 = math.sin(langle-ad)
e1 = -((2*math.pi*f1*time)-ad)/math.tan(langle)
x3 = np.exp(e1)
Icurrent = (V/Z)*((x2*x3)+x1)
g=len(time)
amplitude3=V*sqrt(2)*(np.sin(2*math.pi*f1*time))

```

$$\therefore i_0 = \frac{\sqrt{2}V_i}{Z} \left[\sin(\phi - \alpha) e^{-\frac{(\omega t - \alpha)}{\tan \phi}} + \sin(\omega t - \phi) \right]$$

$i_0 = 0$ otherwise.